Math 211 - Written HW 4

due date: 10PM Monday 02/26/2024

Learning Objectives

1. Computational Practice: This week, we covered matrix inverses and determinants

and how to compute them. Problems 1 and 2 will give you additional methods to

compute these. Try them out and see which method suits your computational style.

Additional computational practice problems are also available on Webwork.

2. Conceptual Review and Mastery: Last week, we covered vector spaces, subspaces,

and linear combinations. Problems 3-5 review these concepts with a heavier focus on

building your theoretical understanding and mathematical intuition.

3. Practice with Abstract Notation and Communication: Last week, we saw how

set notation is used to write/encode vector spaces and subspaces. Problems 3 and 4

help you practice translating between (written) set notation and (spoken/speakable)

"natural language".

4. Value Understanding over Rote Computation: Last week, we covered how to

compute RREFs to answer questions about linear combinations and span. Problem

5 will explicitly ask you to forego these algorithmic methods and use your conceptual

understanding instead. Remember: if algorithms are problems solving procedures, the

fastest algorithm is the one that doesn't have to run at all!

Problem 1. [Basket weaving for 3×3 determinants] An alternative method for computing the determinant of a 3×3 matrix:

$$\mathbf{A} = \begin{bmatrix} a & b & c \\ d & e & f \\ g & h & i \end{bmatrix}$$

is as follows. First, copy the first two columns of your matrix and put them on the right of the matrix:

Next, add the products of the entries along the "downward moving diagonals" shown below in blue (aei + bfg + cdh):

$$\begin{bmatrix} \mathbf{a} & b & c \\ d & \mathbf{e} & f \\ g & h & \mathbf{i} \end{bmatrix} a & b & \begin{bmatrix} a & \mathbf{b} & c \\ d & e & \mathbf{f} \\ g & h & i \end{bmatrix} a & b & \begin{bmatrix} a & b & \mathbf{c} \\ d & e & \mathbf{f} \\ g & h & i \end{bmatrix} a & b & \\ \mathbf{d} & e & \\ \mathbf{g} & h & i \end{bmatrix} a & \\ \mathbf{d} & e & \\$$

Substract from it the products along the "upward moving diagonals" (-gec - hfa - idb):

$$\begin{bmatrix} a & b & \mathbf{c} \\ d & \mathbf{e} & f \\ \mathbf{g} & h & i \end{bmatrix} a \quad b \qquad \begin{bmatrix} a & b & c \\ d & e & \mathbf{f} \\ g & \mathbf{h} & i \end{bmatrix} a \quad b \qquad \begin{bmatrix} a & b & c \\ d & e & f \\ g & h & i \end{bmatrix} a \quad \mathbf{b}$$

Ultimately you get $det(\mathbf{A}) = aei + bfg + cdh - gec - hfa - idb$.

Use the method above to answer the following question without performing any row reduction. State all values of k which make the following matrix invertible:

$$\mathbf{B} = \begin{bmatrix} 1 & 0 & k \\ 0 & k & 1 \\ k & 0 & 9 \end{bmatrix}.$$

Definition. For an $n \times n$ matrix \mathbf{A} , recall that the (i, j)-th minor of \mathbf{A} (denoted $A_{i,j}$) is the matrix obtained by deleting row i and column j. The (i, j)-th cofactor of \mathbf{A} (denoted $c_{i,j}$) is the determinant of $A_{i,j}$ multiplied by the (i, j)-th entry of the sign matrix of \mathbf{A} . Namely:

$$c_{i,j} = (-1)^{i+j} \det(A_{i,j}).$$

So for example, the matrix:

$$\mathbf{B} = \begin{bmatrix} -1 & 1 & 0 \\ -2 & 2 & -5 \\ 3 & 1 & 1 \end{bmatrix} \quad \rightsquigarrow \quad \text{sign matrix} = \begin{bmatrix} + & - & + \\ - & + & - \\ + & - & + \end{bmatrix},$$

the (3,2) minor and cofactor of **B** are:

$$B_{3,2} = \begin{bmatrix} -1 & 0 \\ -2 & -5 \end{bmatrix} \quad \rightsquigarrow \quad c_{3,2} = (-1)\det(B_{3,2}) = -5.$$

Problem 2. [A formula for matrix inverses] Given an $n \times n$ matrix \mathbf{A} , the "matrix of cofactors" of \mathbf{A} is the $n \times n$ matrix whose (i, j)-th entry is the cofactor $c_{i,j}$. We will denote the matrix of cofactors of \mathbf{A} by $\tilde{\mathbf{A}}$.

If **A** is invertible, then its inverse is given by the formula:

$$\mathbf{A}^{-1} = \frac{1}{\det(\mathbf{A})} \tilde{\mathbf{A}}^\mathsf{T}.$$

Notice we are taking the *transpose* of the matrix of cofactors.

(a) Use the formula above to write down a general formula for the inverse of an invertible 2×2 matrix:

$$\mathbf{A} = \begin{bmatrix} a & b \\ c & d \end{bmatrix}.$$

(b) Use the formula above to compute the inverse of the matrix:

$$\mathbf{B} = \begin{bmatrix} 1 & 0 & 2 \\ 2 & 2 & 3 \\ 1 & 1 & 1 \end{bmatrix}.$$

Problem 3. [Identifying vector subspaces] Each of the following sets (a)-(f) is a subset of a vector space we introduced last week.

- (a) The set of vectors in \mathbb{R}^2 in the first quadrant.
- (b) The set of polynomials of degree exactly 2.
- (c) The set of polynomials of even degree.
- (d) The set of 2×2 matrices of determinant equal to zero.
- (e) The set of 2×2 invertible matrices.
- (f) The set of continuous functions $f:[0,1]\to\mathbb{R}$ such that f(0)=1.

For each set above, please:

- 1. Identify a vector space that contains the set.
- 2. Rewrite the set using set notation. Here is an example with various possible solutions:

"the set of vectors in
$$\mathbb{R}^2$$
 with second entry zero" $\iff \{(x,y) \in \mathbb{R}^2 \mid y=0\}$ $\iff \{(x,0) \in \mathbb{R}^2\}$ $\iff \{(x,0) \mid x \in \mathbb{R}\}$

3. Determine whether the set is a subspace of the vector space you listed in part 1. Justify your answer.

Problem 4. [Proving subspaces] For each of the following, prove that W is a subspace of V. For full points, your proofs should be neat, organized, and use full sentences.

(a)
$$V = \mathcal{P}_3(\mathbb{R}) = \{ p(x) = a_3 x^3 + a_2 x^2 + a_1 x + a_0 \mid a_0, a_1, a_2, a_3 \in \mathbb{R} \}$$

 $W = \{ p(x) \in \mathcal{P}_3(\mathbb{R}) \mid p(0) = 0 \}.$

(b)
$$V = \mathsf{M}_{2,2}(\mathbb{R}) = \left\{ \mathbf{A} = \begin{bmatrix} a & b \\ c & d \end{bmatrix} \middle| a, b, c, d \in \mathbb{R} \right\}$$

$$W = \left\{ \mathbf{A} = \begin{bmatrix} a & b \\ c & d \end{bmatrix} \in \mathsf{M}_{2,2}(\mathbb{R}) \middle| a + d = 0 \right\}.$$

(c)
$$V = \mathcal{C}[0, 1] = \{\text{continuous functions } [0, 1] \to \mathbb{R}\}.$$

 $W = \{f \in \mathcal{C}[0, 1] \mid f(0) = f(1) = 0\}.$

Problem 5. [Computation-free linear combinations] Consider the following vectors in \mathbb{R}^3 :

$$\tilde{\mathbf{x}} = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$$
 $\tilde{\mathbf{y}} = \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}$ $\tilde{\mathbf{z}} = \begin{bmatrix} 2 \\ 1 \\ 4 \end{bmatrix}$ $\tilde{\mathbf{w}} = \begin{bmatrix} 6 \\ 2 \\ 8 \end{bmatrix}$.

- (a) Set up a system of linear equations to answer the following question: Is the vector $\tilde{\mathbf{b}} = (9, 5, 17) \in \mathbb{R}^3$ a linear combination of $\tilde{\mathbf{x}}, \tilde{\mathbf{y}}, \tilde{\mathbf{z}}, \tilde{\mathbf{w}}$?
- (b) Without performing any further computation, answer the following: Is $\tilde{\mathbf{b}} = (9, 5, 17)$ a linear combination of $\tilde{\mathbf{x}}, \tilde{\mathbf{y}}, \tilde{\mathbf{z}}, \tilde{\mathbf{w}}$? Justify your answer.
- (c) Fill in the blank: Given a list of vectors $\tilde{\mathbf{x_1}}, \dots, \tilde{\mathbf{x_m}}$ in \mathbb{R}^n , every single vector $\tilde{\mathbf{b}} \in \mathbb{R}^n$ is a linear combination of $\tilde{\mathbf{x_1}}, \dots, \tilde{\mathbf{x_m}}$ precisely when the RREF of the matrix with $\tilde{\mathbf{x_1}}, \dots, \tilde{\mathbf{x_m}}$ as its columns has ______.